

Dual variables and variational principles for Hamiltonian PDEs

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2 Duality of Hamiltonian and symplectic operators

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Motivation

Lagrangian multiform theory (aka pluri-Lagrangian systems)

Variational principle for hierarchies of PDEs.

First step to construct: find a Lagrangian for one member of the hierarchy.

Example: KdV equation $u_t = u_{xxx} + 3uu_x$

- ▶ Traditional EL equations do not produce scalar evolutionary equations.
- ▶ Could try differentiating:

$$u_{xt} = u_{xxx} + 3uu_{xx} + 3u_x$$

but still not an EL equation

- ▶ Need to pass to potential variable, $u = \bar{u}_x$:

$$\bar{u}_{xt} = \bar{u}_{xxxx} + 3\bar{u}_x \bar{u}_{xx}$$

is EL equation of $\mathcal{L} = \frac{1}{2} \bar{u}_t \bar{u}_x - \frac{1}{2} \bar{u}_x \bar{u}_{xxx} - \bar{u}_x^3$.

Motivation

Why is \bar{u} the right variable?

Are there other ways to make a Hamiltonian PDE Lagrangian?

Dorfman. Dirac structures of integrable evolution equations. 1987.

Dirac structures generalise both Hamiltonian and symplectic operators, which are key ingredients in the Hamiltonian resp. Lagrangian formulation.

Mokhov. Symplectic and Poisson structures on loop spaces of smooth manifolds, and integrable systems. 1998.

Studies relations between invertible symplectic operators and Hamiltonian operators, considers classification problems, gives examples of bi-Lagrangian structures.

Nutku & Pavlov. Multi-Lagrangians for integrable systems. 2002.

Many examples of integrable PDEs with several non-equivalent Lagrangians, but the strategy to obtain them is not clearly explained.

Bustamante & Hojman. 2003. Pavlov, Vitolo. 2017.

Hamiltonian systems

In mechanics: $i_X\omega = dH$

Symplectic form ω defines an operator $\Omega : TQ \rightarrow T^*Q$

$$\Omega X = dH \quad (\text{symplectic})$$

Non-degeneracy of ω implies that Ω is invertible, $A = \Omega^{-1} : T^*Q \rightarrow TQ$

$$X = AdH \quad (\text{Poisson})$$

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In classical field theory: (Poisson) generalises to

$$u_t = \mathcal{A} \frac{\delta H}{\delta u}$$

\mathcal{A} may not be invertible, so cannot write analogue of (symplectic).

Example: KdV can be written as

$$u_t = \partial_x(u_{xx} + \frac{3}{2}u^2) = \mathcal{A} \frac{\delta H}{\delta u}$$

with $\mathcal{A} = \partial_x$ and $H = -\frac{1}{2}u_x^2 + \frac{1}{2}u^3$.

Lagrangian mechanics in phase space

Lagrangian description of

$$\Omega \mathbf{z}_t = \nabla H(\mathbf{z})$$

Variational principle in phase space:

$$\mathcal{L} = \frac{1}{2} \mathbf{z}^\top \Omega \mathbf{z}_t - H(\mathbf{z})$$

In Darboux coordinates,

$$\mathcal{L} = \sum_i q^i p_i - H$$

$$(\mathbf{z} : \mathbb{R} \rightarrow T^*Q)$$

Lagrangian description of

$$\mathbf{z}_t = A \nabla H(\mathbf{z})$$

Introduce new variables $\bar{\mathbf{z}}$ by

$$\mathbf{z} = A \bar{\mathbf{z}}$$

If A is constant: $\nabla_{\bar{\mathbf{z}}} = A^\top \nabla_{\mathbf{z}}$.

If A is skew-symmetric:

$$\begin{aligned} A \bar{\mathbf{z}}_t &= A \nabla_{\mathbf{z}} H(\mathbf{z}) \\ &= -\nabla_{\bar{\mathbf{z}}} (H(A \bar{\mathbf{z}})) \end{aligned}$$

which is the EL equation of

$$\mathcal{L} = \frac{1}{2} \bar{\mathbf{z}}^\top A \bar{\mathbf{z}}_t + H(\bar{\mathbf{z}})$$

Does this generalise to Hamiltonian PDEs $u_t = \mathcal{A} \frac{\delta H}{\delta u}$?

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Potential variable as dual space variable

- ▶ Space of independent (space-)variables \mathbb{R}^m .
- ▶ Dependent variables take values in vector space U .
- ▶ Dual space \bar{U} , bilinear pairing $\langle \cdot, \cdot \rangle : U \times \bar{U} \rightarrow \mathbb{R}$.
- ▶ Phase space $\mathcal{F} = \{\mathbb{R}^m \rightarrow U \mid \text{smooth, rapidly decreasing}\}$,
and dual $\bar{\mathcal{F}} = \{\mathbb{R}^m \rightarrow \bar{U} \mid \text{smooth, rapidly decreasing}\}$.
- ▶ Pairing extends to $\langle \cdot, \cdot \rangle : \mathcal{F} \times \bar{\mathcal{F}} \rightarrow C^\infty(\mathbb{R}^m, \mathbb{R})$.
 $\int \langle \cdot, \cdot \rangle d^m x : \mathcal{F} \times \bar{\mathcal{F}} \rightarrow \mathbb{R}$.

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Fibre of $T\mathcal{F}$ can be identified with \mathcal{F} , fibre of $T^*\mathcal{F}$ with $\bar{\mathcal{F}}$.

Hamiltonian operator on \mathcal{F} : fibre-preserving map $\mathcal{A} : \Gamma(T^*\mathcal{F}) \rightarrow \Gamma(T\mathcal{F})$
from 1-forms to vector fields, satisfying certain conditions.

Constant Hamiltonian operator: $\mathcal{A} : \bar{\mathcal{F}} \rightarrow \mathcal{F}$.

Potential Hamiltonian variable \bar{u} , defined by $u = \mathcal{A}\bar{u}$

The phase space is now $\bar{\mathcal{F}}$. \bar{U} becomes the primary space and U the dual.

Hamiltonian and symplectic operators

$\mathcal{A} : \bar{\mathcal{F}} \rightarrow \mathcal{F}$ is a constant Hamiltonian operator on \mathcal{F} if

- ▶ \mathcal{A} is skew-adjoint: $\int \langle f, \mathcal{A}g \rangle d^m x = - \int \langle \mathcal{A}f, g \rangle d^m x$, where $f, g \in \bar{\mathcal{F}}$
- ▶ $\{F, G\}_{\mathcal{F}} := \int \langle \frac{\delta F}{\delta u}, \mathcal{A} \frac{\delta G}{\delta u} \rangle d^m x$ satisfies the Jacobi identity,
where $F, G : \mathcal{F} \rightarrow \mathbb{R}$ and $\frac{\delta F}{\delta u}, \frac{\delta G}{\delta u} : \mathcal{F} \rightarrow \bar{\mathcal{F}}$

$\mathcal{J} : \mathcal{F} \rightarrow \bar{\mathcal{F}}$ is a constant symplectic operator on \mathcal{F} if

- ▶ \mathcal{J} is skew-adjoint: $\int \langle X, \mathcal{J}Y \rangle d^m x = - \int \langle \mathcal{J}X, Y \rangle d^m x$,
- ▶ $\omega(X, Y) := \int \langle X, \mathcal{J}Y \rangle d^m x$ defines a closed 2-form,
where $X, Y : \mathcal{F} \rightarrow \mathcal{F}$

The following are equivalent:

- ▶ \mathcal{J} is symplectic
- ▶ there exists a $p[u] = p(u, u_x, u_{xx}, \dots)$ such that $\mathcal{J} = \ell_p^* - \ell_p$
- ▶ $\mathcal{J}u_t$ is the Euler-Lagrange expression of $\mathcal{L} = p[u]u_t$

In particular, $\mathcal{J}u_t = -\frac{\delta H}{\delta u}$ is an Euler-Lagrange equation if \mathcal{J} is symplectic.

Relating Hamiltonian and symplectic operators

Theorem [e.g. Mokhov, 1998]

\mathcal{A} is a Hamiltonian operator if and only if \mathcal{A}^{-1} is a symplectic operator

Proof idea: Find vectors X, Y, Z and functionals F, G, H such that
 $d\omega(X, Y, Z) = \{F, \{G, H\}\} + \{G, \{H, F\}\} + \{H, \{F, G\}\}$ ■

Lemma

If $\mathcal{A} : \bar{\mathcal{F}} \rightarrow \mathcal{F}$ is a constant Hamiltonian operator on \mathcal{F} and $H : \mathcal{F} \rightarrow \mathbb{R}$, then

$$\frac{\delta H \circ \mathcal{A}}{\delta \bar{u}} = \mathcal{A}^* \frac{\delta H}{\delta u}$$

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$$\frac{\delta H \circ \mathcal{A}}{\delta \bar{u}} = \mathcal{A}^* \frac{\delta H}{\delta u} = -\mathcal{A} \frac{\delta H}{\delta u}$$

If \mathcal{A} is constant and invertible, the Lemma allows us to identify the bracket

$$\{F, G\}_{\bar{\mathcal{F}}} := \int \left\langle \frac{\delta F}{\delta \bar{u}}, \mathcal{A}^{-1} \frac{\delta G}{\delta \bar{u}} \right\rangle d^m x$$

with the Poisson bracket $-\{\cdot, \cdot\}_{\mathcal{F}}$, so \mathcal{A}^{-1} is a Hamiltonian operator on $\bar{\mathcal{F}}$
and \mathcal{A} is a symplectic operator on $\bar{\mathcal{F}}$

Express $u_t = \mathcal{A} \frac{\delta H}{\delta u}$ wrt potential Hamiltonian variable

Using $u = \mathcal{A}\bar{u}$ and the Lemma:

$$u_t = \mathcal{A} \frac{\delta H[u]}{\delta u} \implies \mathcal{A}\bar{u}_t = -\frac{\delta H[\mathcal{A}\bar{u}]}{\delta \bar{u}}$$

Since \mathcal{A} is a symplectic operator on $\bar{\mathcal{F}}$, this is the EL equation of a Lagrangian of the form

$$\mathcal{L} = \rho[\bar{u}]\bar{u}_t - H[\mathcal{A}\bar{u}]$$

The same conclusion holds if \mathcal{A} is only surjective (and constant).

Switching to the potential Hamiltonian variable \bar{u}

- ▶ switches the roles of \mathcal{F} and $\bar{\mathcal{F}}$,
- ▶ turns the Hamiltonian operator \mathcal{A} into a symplectic operator,
- ▶ turns a Hamiltonian PDE into an EL equation.

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Example: KdV

$u_t = u_{xxx} + 3uu_x$ can be written as

$$u_t = \partial_x(u_{xx} + \frac{3}{2}u^2) = \partial_x \frac{\delta}{\delta u}(-\frac{1}{2}u_x^2 + \frac{1}{2}u^3)$$

$$u_t = (\partial_x^3 + 2u\partial_x + u_x)(u) = (\partial_x^3 + 2u\partial_x + u_x) \frac{\delta}{\delta u}(\frac{1}{2}u^2)$$

Use $\mathcal{A} = \partial_x$ to define potential variable, $u = \bar{u}_x$.

Not just \mathcal{A} , but also $\mathcal{B} = \partial_x^3 + 2\bar{u}_x\partial_x + \bar{u}_x$ is symplectic in \bar{u} -variables.

We have two Lagrangians:

$$\begin{aligned}\mathcal{L}_A &= \frac{1}{2}\bar{u}_x\bar{u}_t - (-\frac{1}{2}\bar{u}_{xx}^2 + \frac{1}{2}\bar{u}_x^3) \\ \mathcal{L}_B &= \frac{1}{2}(\bar{u}_{xxx} + \bar{u}_x^2)\bar{u}_t - (\frac{5}{8}\bar{u}_x^4 - \frac{5}{2}\bar{u}_x\bar{u}_{xx}^2 + \frac{1}{2}\bar{u}_{xxx}^2)\end{aligned}$$

with EL equations

$$\mathcal{A}(-u_t + \bar{u}_{xxx} + \frac{3}{2}\bar{u}_x^2) = 0$$

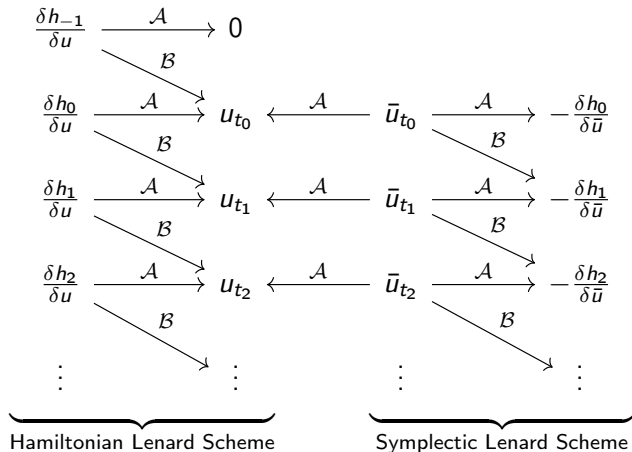
$$\mathcal{B}(-u_t + \bar{u}_{xxx} + \frac{3}{2}\bar{u}_x^2) = 0.$$

Double Lenard scheme

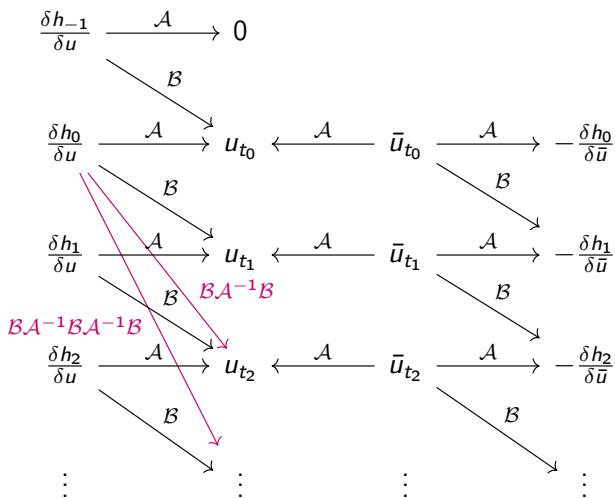
\mathcal{A}, \mathcal{B} Hamiltonian pair, \mathcal{A} constant,

$$u = \mathcal{A}\bar{u},$$

h_{-1} a Casimir of \mathcal{A} .



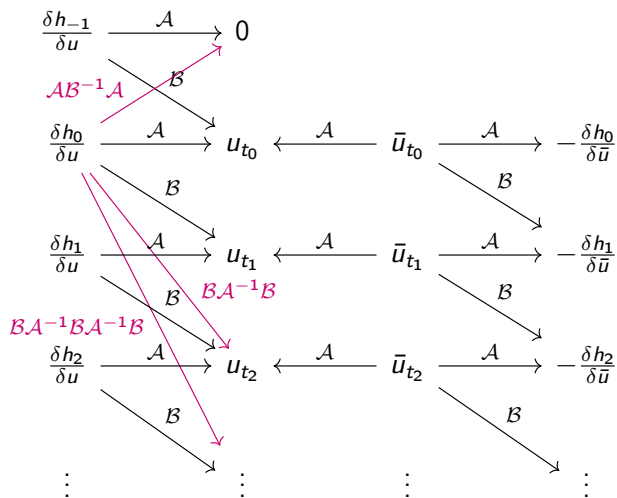
Hamiltonian recursion



Hierarchy of Hamiltonian operators obtained by recursion operator $\mathcal{B}\mathcal{A}^{-1}$:

$$\mathcal{A}, \mathcal{B}, \mathcal{B}\mathcal{A}^{-1}\mathcal{B}, \mathcal{B}\mathcal{A}^{-1}\mathcal{B}\mathcal{A}^{-1}\mathcal{B}, \dots$$

Hamiltonian recursion



Hierarchy of Hamiltonian operators obtained by recursion operator $\mathcal{B}\mathcal{A}^{-1}$:

$$\dots, AB^{-1}A, \quad A, B, BA^{-1}B, BA^{-1}BA^{-1}B, \dots$$

Hamiltonian operators on \mathcal{F} and $\bar{\mathcal{F}}$

Lemma

If \mathcal{D} is a Hamiltonian operator on \mathcal{F} (i.e. wrt u),
then $\mathcal{A}^{-1}\mathcal{D}\mathcal{A}^{-1}$ is a Hamiltonian operator on $\bar{\mathcal{F}}$ (i.e. wrt \bar{u})

Proof. Recall that $\frac{\delta F}{\delta \bar{u}} = -\mathcal{A}\frac{\delta F}{\delta u}$ so

$$\{F, G\} = \int \frac{\delta F}{\delta u} \mathcal{D} \frac{\delta G}{\delta u} d^m x = - \int \frac{\delta F}{\delta \bar{u}} \mathcal{A}^{-1} \mathcal{D} \mathcal{A}^{-1} \frac{\delta G}{\delta \bar{u}} d^m x \quad \blacksquare$$

$\mathcal{D} = \mathcal{A} \rightarrow \mathcal{A}^{-1}$ Hamiltonian for \bar{u} , \mathcal{A} symplectic for \bar{u}

$\mathcal{D} = \mathcal{B} \rightarrow \mathcal{A}^{-1}\mathcal{B}\mathcal{A}^{-1}$ Hamiltonian for \bar{u} , $\mathcal{A}\mathcal{B}^{-1}\mathcal{A}$ symplectic for \bar{u}

$\mathcal{D} = \mathcal{A}\mathcal{B}^{-1}\mathcal{A} \rightarrow \mathcal{B}^{-1}$ Hamiltonian for \bar{u} , \mathcal{B} symplectic for \bar{u}

$$\begin{array}{ccccccc}
 \frac{\delta h_i}{\delta u} & \xrightarrow[\mathcal{B}]{\mathcal{A}} & u_{t_i} & \xleftarrow{\mathcal{A}} & \bar{u}_{t_i} & \xrightarrow{\mathcal{A}} & -\frac{\delta h_i}{\delta \bar{u}} \\
 & \searrow^{\mathcal{A}\mathcal{B}^{-1}\mathcal{A}} & & & & \searrow^{\mathcal{B}} & \\
 \frac{\delta h_{i+1}}{\delta u} & \xrightarrow{\mathcal{A}} & u_{t_{i+1}} & \xleftarrow{\mathcal{A}} & \bar{u}_{t_{i+1}} & \xrightarrow{\mathcal{A}} & -\frac{\delta h_{i+1}}{\delta \bar{u}}
 \end{array}$$

Dual picture

$$\begin{array}{ccccccc}
 \frac{\delta h_i}{\delta u} & \xrightarrow{\mathcal{A}} & u_{t_i} & \xleftarrow{\mathcal{A}} & \bar{u}_{t_i} & \xrightarrow{\mathcal{A}} & -\frac{\delta h_i}{\delta \bar{u}} \\
 & \searrow^{\mathcal{B}} & \nearrow^{\mathcal{A}\mathcal{B}^{-1}\mathcal{A}} & & \searrow^{\mathcal{B}} & & \\
 \frac{\delta h_{i+1}}{\delta u} & \xrightarrow{\mathcal{A}} & u_{t_{i+1}} & \xleftarrow{\mathcal{A}} & \bar{u}_{t_{i+1}} & \xrightarrow{\mathcal{A}} & -\frac{\delta h_{i+1}}{\delta \bar{u}}
 \end{array}$$

- ▶ $\mathcal{A} : T\bar{\mathcal{F}} \rightarrow T^*\bar{\mathcal{F}}$ is symplectic on $\bar{\mathcal{F}}$ and dual to $\mathcal{A} : T^*\mathcal{F} \rightarrow T\mathcal{F}$:

$$u_{t_i} = \mathcal{A} \frac{\delta h_i}{\delta u} \quad \text{and} \quad \mathcal{A} \bar{u}_{t_i} = \frac{\delta h_i}{\delta \bar{u}}$$

- ▶ $\mathcal{B} : T\bar{\mathcal{F}} \rightarrow T^*\bar{\mathcal{F}}$ is symplectic on $\bar{\mathcal{F}}$ but dual to $\mathcal{A}\mathcal{B}^{-1}\mathcal{A}$, not to \mathcal{B} :

$$u_{t_i} = \mathcal{B} \frac{\delta h_{i-1}}{\delta u} \quad \text{but} \quad \mathcal{B} \bar{u}_{t_i} = \frac{\delta h_{i+1}}{\delta \bar{u}}$$

- ▶ Could also consider $\mathcal{B}\mathcal{A}^{-1}\mathcal{B}, \dots$, as symplectic operators for \bar{u} .

Each of these leads to different Lagrangians in \bar{u} -variables.

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Other examples

Nutku & Pavlov. Multi-Lagrangians for integrable systems. 2002.

Present bi-Lagrangians for

- ▶ KdV
- ▶ polytropic gas dynamics
- ▶ Kaup-Boussinesq
- ▶ NLS
- ▶ ...

These are the same Lagrangians as we find, but their presentation suggest some educated guesswork was involved.

We seem to have a general method.

Implications in Lagrangian multiform theory

Lagrangian multiforms for 2d PDEs

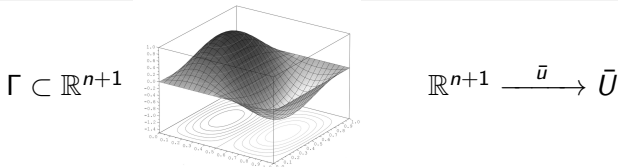
Consider functions $\bar{u} = \bar{u}(t_0 = x, t_1, t_2, \dots, t_n)$ of multi-time.

Jet-dependent 2-form $\mathcal{L} = \sum_{i < j} L_{ij}[\bar{u}] dt^i \wedge dt^j$.

For every surface $\Gamma \in \mathbb{R}^{n+1}$, consider the action

$$S_{\Gamma}[\bar{u}] = \int_{\Gamma} \mathcal{L}[\bar{u}]$$

and require that all these actions are critical with respect to variations of both Γ and u .



Particular case: take Γ to be the (t_i, t_j) -plane, then $S_{\Gamma} = \int L_{ij}[\bar{u}] dt^i \wedge dt^j$

Implications in Lagrangian multiform theory

Suppose we have commuting PDEs

$$\bar{u}_{t_j} - Q_j[\bar{u}] = 0, \quad j = 1, 2, \dots$$

and we know Lagrangians $L_{0j}[\bar{u}]$ for each of these, all with the same symplectic operator \mathcal{J} , so they have EL equations of the form

$$\mathcal{J}(\bar{u}_{t_j} - Q_j[\bar{u}]) = 0, \quad j = 1, 2, \dots$$

Then we can construct the remaining coefficients L_{ij} ($i, j > 0$) so that

the system of multiform Euler-Lagrange equations is equivalent to

$$\bar{u}_{t_j} - Q_j[\bar{u}] = 0, \quad j = 1, 2, \dots$$

For each symplectic operator $\mathcal{A}, \mathcal{B}, \dots$ we find a Lagrangian 2-form \mathcal{L}

Idea of the construction: find L_{ij} such that the exterior derivative $d\mathcal{L} = \sum_{i < j < k} P_{ijk} dt^i \wedge dt^j \wedge dt^k$ attains a “double zero” on the equation:

$$P_{1jk} = (\bar{u}_{t_j} - Q_j[\bar{u}])\mathcal{J}(\bar{u}_{t_k} - Q_k[\bar{u}]) - (\bar{u}_{t_k} - Q_k[\bar{u}])\mathcal{J}(\bar{u}_{t_j} - Q_j[\bar{u}])$$

Can we forget about the Hamiltonian side?

How to express the compatibility of two Lagrangians / two multiforms / two symplectic operators?

Invertible symplectic operators \mathcal{I} and \mathcal{J} are compatible

- ▶ if \mathcal{I}^{-1} and \mathcal{J}^{-1} are compatible Hamiltonian operators
- ▶ if $\mathcal{I}^{-1} + \lambda\mathcal{J}^{-1}$ is Hamiltonian
- ▶ if

$$(\mathcal{I}^{-1} + \lambda\mathcal{J}^{-1})^{-1} = \mathcal{I} + \lambda\mathcal{I}\mathcal{J}^{-1}\mathcal{I} + \lambda^2\mathcal{I}\mathcal{J}^{-1}\mathcal{I}\mathcal{J}^{-1}\mathcal{I} + \dots$$

is symplectic

- ▶ if \mathcal{I} , $\mathcal{I}\mathcal{J}^{-1}\mathcal{I}$, $\mathcal{I}\mathcal{J}^{-1}\mathcal{I}\mathcal{J}^{-1}\mathcal{I}$, \dots are symplectic
- ▶ if $\mathcal{I}\mathcal{J}^{-1}$ is a Nijenhuis operator

Conclusions

- ▶ A “potential” variable should be defined by a Hamiltonian operator. It is in a space dual to the original variable.
- ▶ This allows us to transform Hamiltonian operators into symplectic operators and find Lagrangians
- ▶ In the traditional calculus of variations, the “higher Lagrangians” give increasingly weak differential consequences.
In Lagrangian multiform theory, all give evolutionary equations.

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Thank you for your attention!